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Oscillations about different axes:

$$H = \frac{\Omega}{2} \sigma_z + \epsilon \cos(\omega t + \varphi) \sigma_x = \vec{m}(t) \cdot \vec{\sigma} \quad \vec{m}(t) = \begin{pmatrix} \epsilon \cos \omega t + \varphi \\ 0 \\ \frac{\Omega}{2} \end{pmatrix}$$

$$\vec{m}(t) = \frac{1}{2} \begin{pmatrix} \epsilon \cos(\omega t + \varphi) \\ \epsilon \sin(\omega t + \varphi) \\ \frac{\Omega}{2} \end{pmatrix} + \frac{1}{2} \begin{pmatrix} \epsilon \cos(\omega t + \varphi) \\ -\epsilon \sin(\omega t + \varphi) \\ \frac{\Omega}{2} \end{pmatrix}$$

RWA

$$H = \frac{\Omega}{2} \sigma_z + \frac{\epsilon}{2} \left[\cos(\omega t + \varphi) \sigma_x + \sin(\omega t + \varphi) \sigma_y \right] + \frac{\epsilon}{2} \left[\cos(\omega t + \varphi) \sigma_x - \sin(\omega t + \varphi) \sigma_y \right]$$

$$U H U^\dagger - i U \dot{U}^\dagger |\phi\rangle = i \hbar \frac{d}{dt} |\phi\rangle$$

Rotating Frame @ ωt : $U = e^{i \frac{\omega}{2} t \sigma_z}$

$$U \sigma_x U^\dagger = \cos \omega t \sigma_x - \sin \omega t \sigma_y$$

$$U \dot{U}^\dagger = -i \frac{\omega}{2} \sigma_z$$

$$U \sigma_y U^\dagger = \sin \omega t \sigma_x + \cos \omega t \sigma_y$$

$$\textcircled{*} = \cos(\omega t + \varphi) (\cos \omega t \sigma_x - \sin \omega t \sigma_y) + \sin(\omega t + \varphi) (\sin \omega t \sigma_x + \cos \omega t \sigma_y)$$

$$\begin{cases} \cos(\omega t + \varphi) = \cos \omega t \cos \varphi - \sin \omega t \sin \varphi \\ \sin(\omega t + \varphi) = \sin \omega t \cos \varphi + \cos \omega t \sin \varphi \end{cases}$$

$$= \sigma_x (\cos \omega t (\cos \omega t \cos \varphi - \sin \omega t \sin \varphi) + \sin \omega t (\sin \omega t \cos \varphi + \cos \omega t \sin \varphi)) +$$

$$+ \sigma_y (-\sin \omega t (\cos \omega t \cos \varphi - \sin \omega t \sin \varphi) + \cos \omega t (\sin \omega t \cos \varphi + \cos \omega t \sin \varphi))$$

$$= \sigma_x (\cos^2 \omega t + \sin^2 \omega t) \cos \varphi + \sigma_y \sin \varphi$$

$$\Rightarrow \tilde{H} = \frac{1}{2} (\Omega - \omega) \sigma_z + \frac{\epsilon \cos \varphi}{2} \sigma_x + \frac{\epsilon \sin \varphi}{2} \sigma_y =$$

$$= \frac{1}{2} (\Omega - \omega) \sigma_z + \frac{\Omega_x}{2} \sigma_x + \frac{\Omega_y}{2} \sigma_y = \frac{1}{2} \vec{m} \cdot \vec{\sigma} = \frac{1}{2} \alpha \vec{n} \cdot \vec{\sigma}$$

$$\alpha = |\vec{m}| = \sqrt{(\Omega - \omega)^2 + \Omega_x^2 + \Omega_y^2}$$

\vec{n} unit vector
 $\vec{n} = \begin{pmatrix} \cos \varphi \sin \theta \\ \sin \varphi \sin \theta \\ \cos \theta \end{pmatrix}$

$\varphi = \arctan \frac{\Omega_y}{\Omega_x}$
 $\theta = \arccos \frac{\Omega - \omega}{\alpha}$

Ramsey Fringes:

- create superposition state by a $\frac{\hbar}{2}$ -pulse
- free evolution for time t
- 2nd $\frac{\hbar}{2}$ -pulse about different axis

State after the first $\frac{\hbar}{2}$ pulse:

$$|g\rangle \rightarrow \left(\frac{\hbar}{2}\right)_\phi : \frac{1}{\sqrt{2}}(|g\rangle - ie^{i\phi}|e\rangle)$$

$$U_{\phi_1} = e^{-i\frac{\alpha t}{2} \vec{n}_1 \cdot \vec{\sigma}} \quad \text{with } \alpha = \frac{\hbar}{2} \quad \vec{n}_1 = \begin{pmatrix} \cos \phi_1 \\ \sin \phi_1 \\ 0 \end{pmatrix}$$

$$U_{\left(\frac{\hbar}{2}\right)_\phi} = \mathbb{1} \cos \frac{\alpha t}{2} - i \vec{n}_1 \cdot \vec{\sigma} \sin \frac{\alpha t}{2} = \frac{1}{\sqrt{2}} (\mathbb{1} - i (\cos \phi_1 \sigma_x + \sin \phi_1 \sigma_y))$$

$$U_{\left(\frac{\hbar}{2}\right)_\phi} |g\rangle = \frac{1}{\sqrt{2}} (|g\rangle - i \cos \phi_1 |e\rangle + \sin \phi_1 |e\rangle) = \frac{1}{\sqrt{2}} (|g\rangle - ie^{i\phi_1} |e\rangle) = \psi_1$$

Free precession: $\epsilon = 0$: $\alpha = |\Omega - \omega| = \Delta$ $\vec{n} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$

$$U_{\text{free}} = e^{-i\frac{|\Delta|t}{2} \sigma_z}$$

$$U_{\text{free}} U_{\left(\frac{\hbar}{2}\right)_\phi} |g\rangle = e^{-i\frac{\Delta t}{2} \sigma_z} \frac{1}{\sqrt{2}} (|g\rangle - ie^{i\phi_1} |e\rangle) = \frac{1}{\sqrt{2}} e^{-i\frac{\Delta t}{2}} |g\rangle - ie^{i(\frac{\Delta t}{2} + \phi_1)} |e\rangle = \alpha$$

Second $\frac{\hbar}{2}$ pulse about ϕ_2 axis

$$U_{\left(\frac{\hbar}{2}\right)_\phi_2} \psi_2 = \frac{1}{2} (\mathbb{1} - i (\cos \phi_2 \sigma_x + \sin \phi_2 \sigma_y)) (e^{-i\frac{\Delta t}{2}} |g\rangle - ie^{i(\frac{\Delta t}{2} + \phi_1)} |e\rangle)$$

$$\sigma_x |g\rangle \rightarrow |e\rangle$$

$$\sigma_y |g\rangle \rightarrow i|e\rangle$$

$$\sigma_x |e\rangle \rightarrow |g\rangle$$

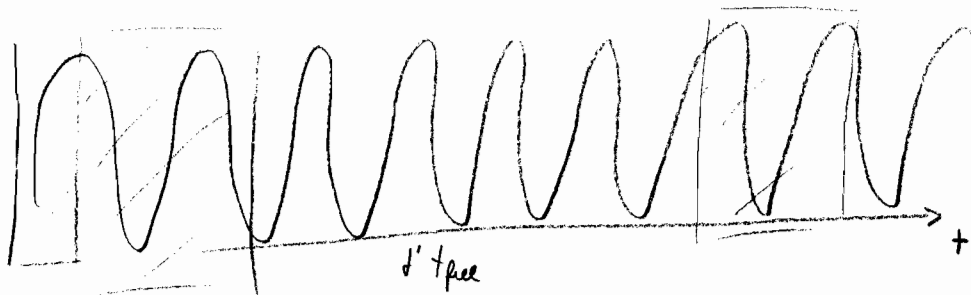
$$\sigma_y |e\rangle \rightarrow -i|g\rangle$$

$$\begin{aligned}
&= \frac{1}{2} \left[e^{-i\frac{\Delta t'}{2}} |g\rangle - i e^{i(\frac{\Delta t'}{2} + \varphi_1)} |e\rangle - i e^{-i\frac{\Delta t'}{2}} (\cos \varphi_2 + i \sin \varphi_2) |e\rangle \right. \\
&\quad \left. - e^{i(\frac{\Delta t'}{2} + \varphi_1)} (\cos \varphi_2 - i \sin \varphi_2) |g\rangle \right] = \\
&= \frac{1}{2} \left[|g\rangle \left(e^{-i\frac{\Delta t'}{2}} - e^{i(\frac{\Delta t'}{2} + \varphi_1 - \varphi_2)} \right) - i |e\rangle \left(e^{i(\frac{\Delta t'}{2} + \varphi_1)} + e^{-i(\frac{\Delta t'}{2} - \varphi_2)} \right) \right] \\
&= \frac{1}{2} \left[e^{i(\varphi_1 - \varphi_2)/2} |g\rangle \left(e^{-i(\Delta t' + \varphi_1 - \varphi_2)/2} - e^{i(\Delta t' + \varphi_1 - \varphi_2)/2} \right) - \right. \\
&\quad \left. i e^{i(\varphi_1 + \varphi_2)/2} |e\rangle \left(e^{i(\Delta t' + \varphi_1 - \varphi_2)/2} + e^{-i(\Delta t' + \varphi_1 - \varphi_2)/2} \right) \right] \\
&\qquad\qquad\qquad \underbrace{\hspace{10em}}_{2\cos(\Delta t' + \Delta\varphi)}
\end{aligned}$$

$$\propto \sin(\Delta t' + \Delta\varphi) |g\rangle + e^{i\varphi_2} \cos(\Delta t' + \Delta\varphi) |e\rangle$$

→ population changes with $\Delta t'$ and $\Delta\varphi$

one source with fixed phase



φ_1

$\varphi_1 + \frac{1}{2}\Delta$

$$\varphi_2 = \varphi_1 + \frac{1}{2}\Delta + t'\Delta$$

←

change either t' or Δ for a change in φ_2

Spin Echo: basic idea: $U^{-1} U |\psi\rangle = |\psi\rangle$

$$U = e^{-\frac{i}{\hbar} H t} \Rightarrow U^{-1} = e^{\frac{i}{\hbar} H t} \Rightarrow \text{time reversal needed}$$

for free-precession Hamiltonian:

$H = \Omega \sigma_z$: change either Ω (possible for spin- $\frac{1}{2}$ in magnetic field)

or swap basis states: $|g\rangle \rightarrow |e\rangle$
 $|e\rangle \rightarrow |g\rangle$

$$|\psi\rangle \rightarrow |\psi'\rangle = \sigma_x |\psi\rangle$$

$$\Rightarrow \hat{H} = U^\dagger H U = \Omega \sigma_x^\dagger \sigma_z \sigma_x = \Omega \sigma_x \sigma_z \sigma_x = -\Omega \sigma_z$$

σ_x : π -pulse

$$\text{Sequence: } U_{\frac{\hbar}{2}} U_{\text{free}} U_{\frac{\hbar}{2}} U_{\text{free}} U_{\frac{\hbar}{2}} \cdot |\psi\rangle = |\psi\rangle$$